

# 第七章

## 带电粒子和电磁场的相互作用

## 本章的思路

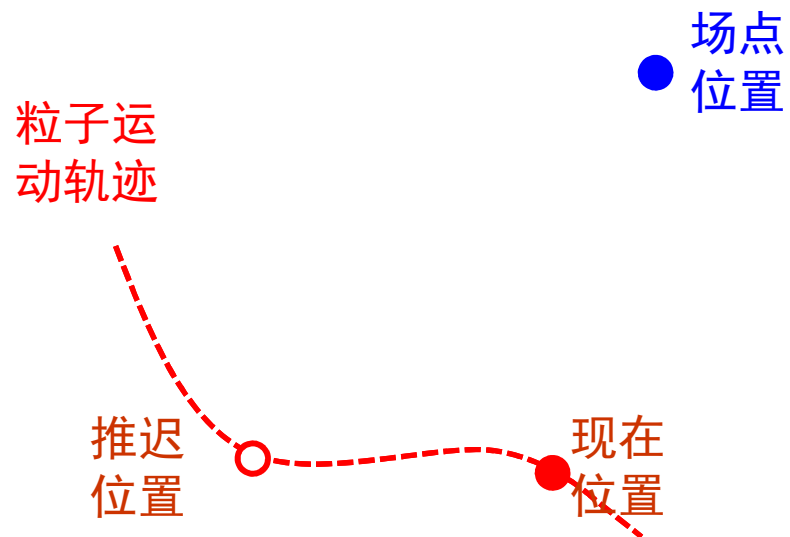
- 经典电动力学——宏观介质电磁现象规律；
- 本章思路：借助经典电动力学，近似处理一个大的带电粒子与电磁场的相互作用，没有考虑量子效应；
- 微观粒子：需要考虑量子效应

# 第一部分：单个带电粒子所激发的辐射电磁场

## § 1 运动带电粒子的势和辐射电磁场

## § 2 高速运动粒子的辐射

## § 4 切伦科夫 (Cerenkov) 辐射



$$\phi(\vec{x}, t) = \int \frac{1}{4\pi\epsilon_0 r} \rho\left(\vec{x}', t - \frac{r}{c}\right) dV'$$

$$\vec{A}(\vec{x}, t) = \frac{1}{4\pi\epsilon_0 c^2} \int \frac{1}{r} \vec{J}\left(\vec{x}', t - \frac{r}{c}\right) dV'$$

## § 1 运动带电粒子的势和辐射电磁场

1. 任意运动带电粒子的势——  
——Lienard-Wiechert势
2. 偶极辐射
3. 任意运动粒子的电磁场

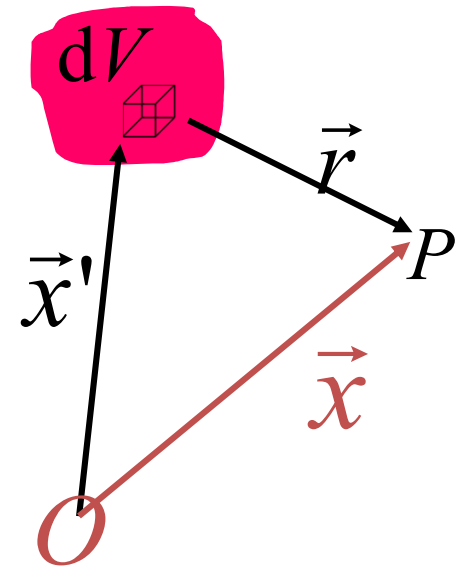
# 1、任意运动带电粒子的势

——Lienard-Wiechert势

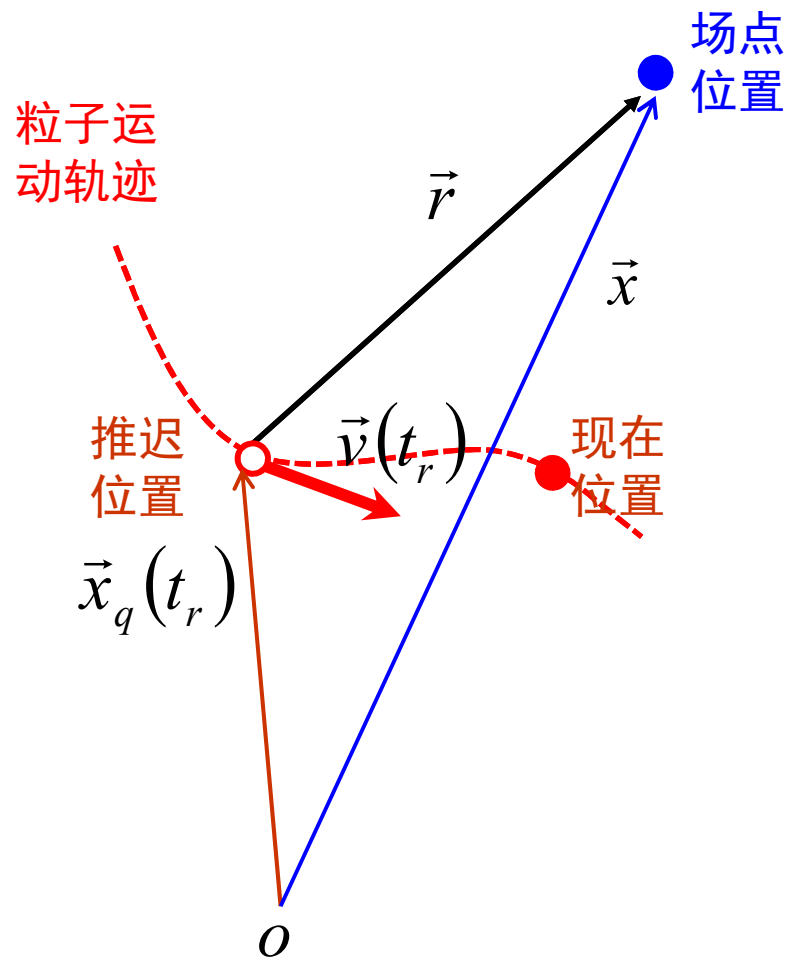
1) 一般地, 给定的电荷、电流分布  $\rho(\vec{x}', t)$ ,  $\vec{J}(\vec{x}', t)$

$$\phi(\vec{x}, t) = \int \frac{1}{4\pi\epsilon_0 r} \rho\left(\vec{x}', t - \frac{r}{c}\right) dV'$$

$$\vec{A}(\vec{x}, t) = \frac{1}{4\pi\epsilon_0 c^2} \int \frac{1}{r} \vec{J}\left(\vec{x}', t - \frac{r}{c}\right) dV'$$



- 对势有贡献的不是同一时刻源区各点的电荷、电流密度值, 而是较早时刻  $(t-r/c)$  的电荷、电流密度值。



$$\phi(\vec{x}, t) = \int \frac{1}{4\pi\epsilon_0 r} \rho\left(\vec{x}', t - \frac{r}{c}\right) dV'$$

$$\vec{A}(\vec{x}, t) = \frac{1}{4\pi\epsilon_0 c^2} \int \frac{1}{r} \vec{J}\left(\vec{x}', t - \frac{r}{c}\right) dV'$$

$$t_r = t - \frac{r}{c}, \quad (t_r : t_{retarded})$$

$$\vec{v}(t_r) = \frac{d\vec{x}_q}{dt_r}$$



- **假设：**把运动的带电粒子看成是小体积内的电荷连续分布的极限：

$$\vec{J}\left(t - \frac{r}{c}\right) dV' = qv\left(t - \frac{r}{c}\right)$$

$v$  为带电粒子在  $t-r/c$  时刻的速度。

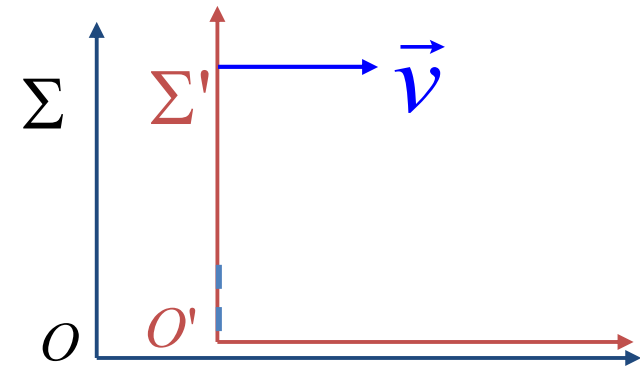
- 借助于惯性参照系之间四维势的变换，得到**任意运动的带电粒子的势表达式**。

$$A_4' = i \frac{\varphi'}{c}$$

在静止参照系  $\Sigma'$  中，点电荷的势：

$$\vec{A}' = 0 \quad \varphi' = \frac{q}{4\pi\epsilon_0 r'}$$

$$A_1' = A_2' = A_3' = 0, \quad A_4' = i \frac{q}{4\pi\epsilon_0 c r'}$$



根据四维矢量的Lorentz变换： $A = \tilde{a} A'$

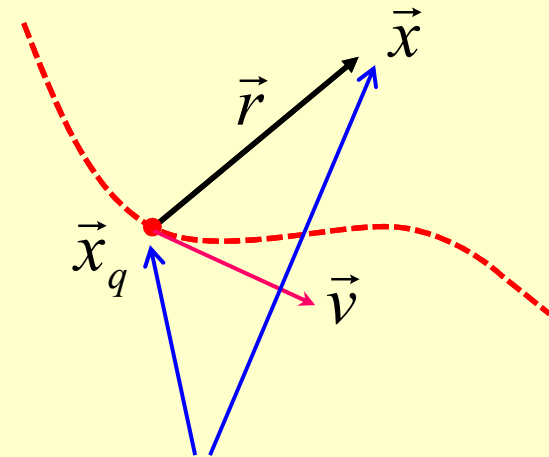
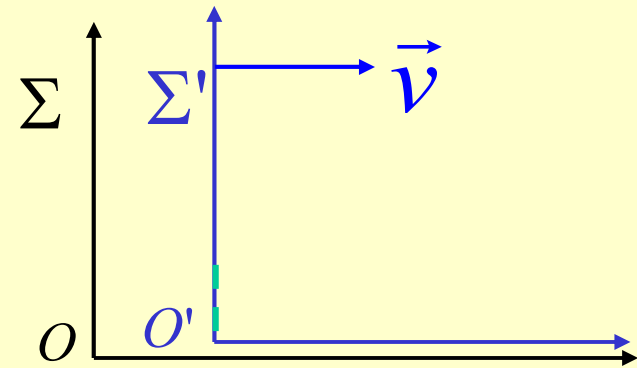
$$\begin{bmatrix} A_1 \\ A_2 \\ A_3 \\ A_4 \end{bmatrix} = \begin{bmatrix} \gamma & 0 & 0 & -i\beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ i\beta\gamma & 0 & 0 & \gamma \end{bmatrix} \cdot \begin{bmatrix} A_1' \\ A_2' \\ A_3' \\ A_4' \end{bmatrix}$$

变换到  $\Sigma$  系，有：

$$\phi = \gamma \frac{q}{4\pi\epsilon_0 r'}$$

$$A_1 = \gamma v \frac{q}{4\pi\epsilon_0 c^2 r'}$$

$$\vec{A} = \gamma \frac{q}{4\pi\epsilon_0 c^2 r'} \vec{v}$$



余下步骤是将  $r'$  用  $\Sigma$  系中的坐标  $r$  表示；

- 在  $\Sigma'$  参照系中:

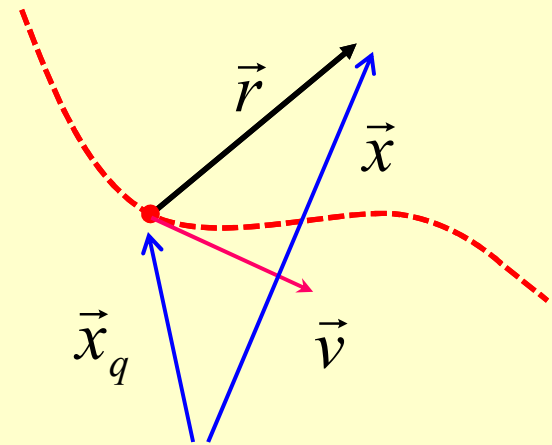
电荷在某时刻  $t_1'$  产生的作用在  $t_2'$  时刻传播到场点所走过的距离

$$r' = c(t_2' - t_1')$$

- 在  $\Sigma$  参照系中:

运动电荷的这种作用的产生和到达, 分别发生在  $t_1$  和  $t_2$  时刻, 则

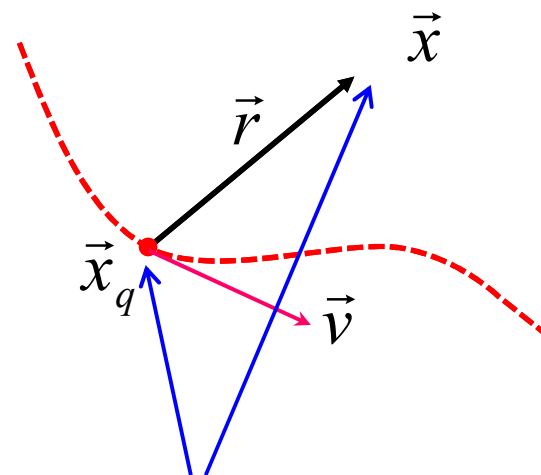
$$r = c(t_2 - t_1) = |\vec{x} - \vec{x}_q|$$



- 当速度  $\vec{v}$  和  $\vec{x}$  轴成一定的角度时，空时坐标的Lorentz变换

$$t' = \gamma \left( t - \frac{v}{c^2} x \right)$$

$$t' = \gamma \left( t - \frac{\vec{v} \cdot \vec{x}}{c^2} \right)$$



- 在两个参照系中电荷的作用从发出-到达的距离存在如下的关系

$$r' = \gamma \left[ c(t_2 - t_1) - \frac{1}{c} \vec{v} \cdot (\vec{x} - \vec{x}_q) \right]$$

$$r' = c(t_2' - t_1')$$

$$r = c(t_2 - t_1)$$

$$r' = \gamma \left( r - \frac{1}{c} \vec{v} \cdot \vec{r} \right)$$

$$\phi = \gamma \frac{1}{4\pi\epsilon_0} \frac{q}{r'}$$

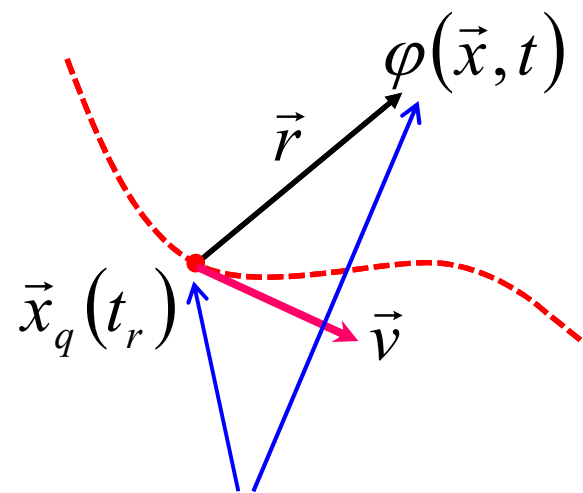
$$\vec{A} = \gamma \frac{1}{4\pi\epsilon_0 c^2} \frac{q\vec{v}}{r'}$$

$$r' = \gamma \left( r - \frac{1}{c} \vec{v} \cdot \vec{r} \right)$$

李纳-维谢尔 (Liénard-Wiechert ) 势：

$$\phi(\vec{x}, t) = \frac{1}{4\pi\epsilon_0} \cdot \frac{q}{r - \frac{1}{c} \vec{v} \cdot \vec{r}}$$

$$\vec{A}(\vec{x}, t) = \frac{1}{4\pi\epsilon_0 c^2} \cdot \frac{q\vec{v}}{r - \frac{1}{c} \vec{v} \cdot \vec{r}}$$



$$\phi(\vec{x}, t) = \frac{1}{4\pi\epsilon_0} \cdot \frac{q}{r - \frac{1}{c} \vec{v} \cdot \vec{r}}$$

$$\vec{E} = -\nabla\phi - \frac{\partial\vec{A}}{\partial t}$$

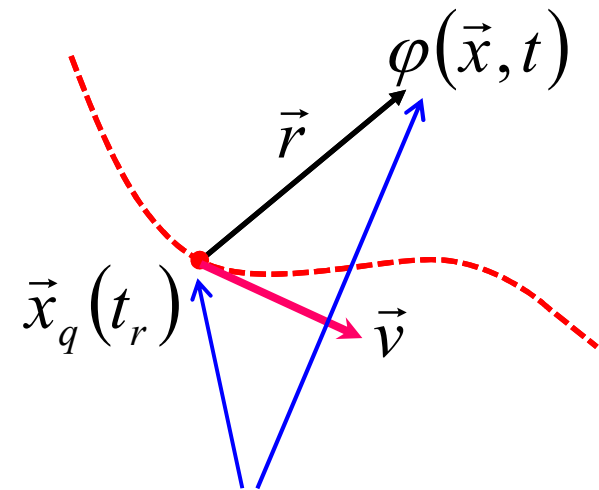
$$\vec{B} = \nabla \times \vec{A}$$

$$\vec{A}(\vec{x}, t) = \frac{1}{4\pi\epsilon_0 c^2} \cdot \frac{q\vec{v}}{r - \frac{1}{c} \vec{v} \cdot \vec{r}}$$

- 需要对势求有关  $x$  和  $t$  的导数，而等式右边是  $t_r$  的函数

$$\vec{r} = \vec{x} - \vec{x}_q(t_r),$$

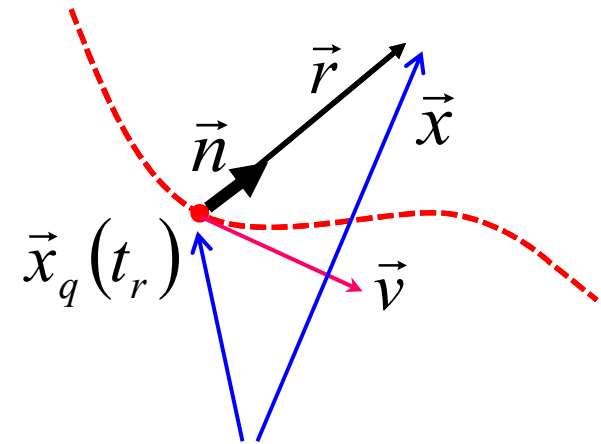
$$t_r = t - \frac{r}{c}$$



$$\vec{E} = -\nabla\phi - \frac{\partial\vec{A}}{\partial t},$$

$$\vec{B} = \nabla \times \vec{A}$$

$$t_r = t - \frac{r}{c}$$

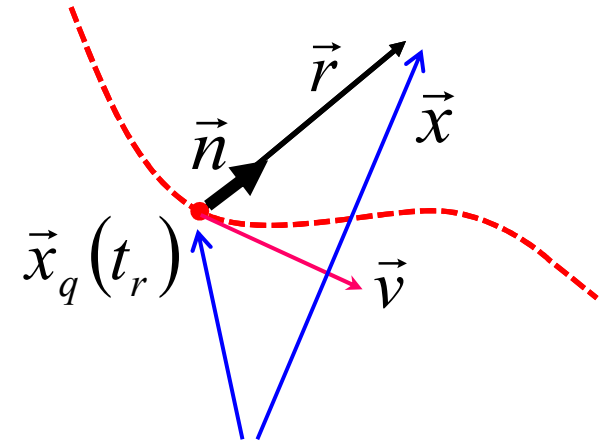




$$\vec{E} = -\nabla\phi - \frac{\partial\vec{A}}{\partial t},$$

$$\vec{B} = \nabla \times \vec{A}$$

$$t_r = t - \frac{r}{c}$$



- 需要考察  $\partial t_r / \partial t = ?$

$$\nabla t_r = ?$$

$$\nabla r$$

$$\nabla(\vec{r} \cdot \vec{v})$$

$$\vec{E} = -\nabla\phi - \frac{\partial\vec{A}}{\partial t}$$

- 先考察  $\partial t_r / \partial t = ?$

$$\vec{B} = \nabla \times \vec{A}$$

$$t_r = t - \frac{r}{c}$$

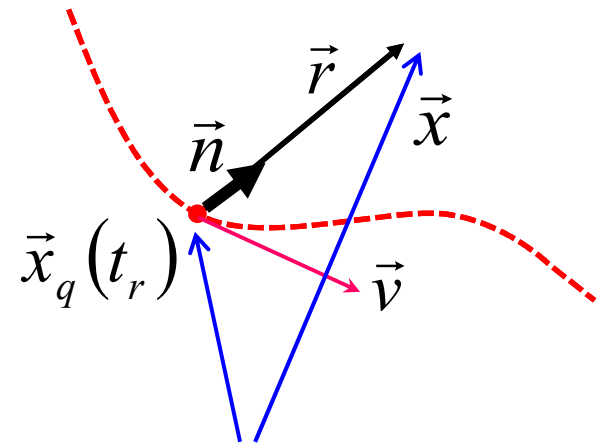
$$\rightarrow \frac{\partial t_r}{\partial t} = 1 - \frac{1}{c} \cdot \frac{\partial r}{\partial t_r} \cdot \frac{\partial t_r}{\partial t}$$

$$\frac{\partial r}{\partial t_r} = \frac{\partial}{\partial t_r} \sqrt{[\vec{x} - \vec{x}_q(t_r)]^2}$$

$$= \frac{1}{2} \cdot \frac{1}{\sqrt{[\vec{x} - \vec{x}_q(t_r)]^2}} \cdot \frac{\partial}{\partial t_r} [\vec{x} - \vec{x}_q(t_r)]^2$$

$$= \frac{1}{2} \cdot \frac{\vec{r}}{r} \cdot 2 \frac{\partial [-\vec{x}_q(t_r)]}{\partial t_r} = -\frac{\vec{r}}{r} \cdot \vec{v},$$

$$\frac{\partial r}{\partial t_r} = -\vec{v} \cdot \vec{n}$$



$$\frac{\partial r}{\partial t_r} = -\vec{v} \cdot \vec{n}$$

$$t_r = t - \frac{r}{c}$$

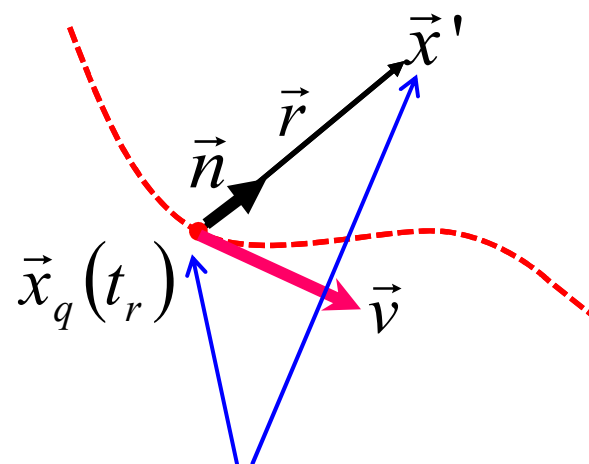
$$\frac{\partial t_r}{\partial t} = 1 - \frac{1}{c} \cdot \frac{\partial r}{\partial t_r} \cdot \frac{\partial t_r}{\partial t}$$

$$\frac{\partial t_r}{\partial t} = 1 - \frac{1}{c} \cdot \frac{\partial r}{\partial t_r} \cdot \frac{\partial t_r}{\partial t} = 1 + \frac{1}{c} (\vec{v} \cdot \vec{n}) \frac{\partial t_r}{\partial t}$$

$$\frac{\partial t_r}{\partial t} \cdot \left( 1 - \frac{\vec{v} \cdot \vec{n}}{c} \right) = 1$$

得到：

$$\frac{\partial t_r}{\partial t} = \left( 1 - \frac{\vec{v} \cdot \vec{n}}{c} \right)^{-1}$$



$$\nabla t_r = ?$$

$$\begin{aligned} \rightarrow \nabla t_r &= -\frac{1}{c} \nabla r = -\frac{1}{c} \nabla r(\vec{x}, t_r) \\ &= -\frac{1}{c} \nabla r \Big|_{t_r = \text{常数}} - \frac{1}{c} \frac{\partial r}{\partial t_r} \nabla t_r \end{aligned}$$

$$= -\frac{1}{c} \frac{\vec{r}}{r} + \frac{1}{c} (\vec{v} \cdot \vec{n}) \nabla t_r$$

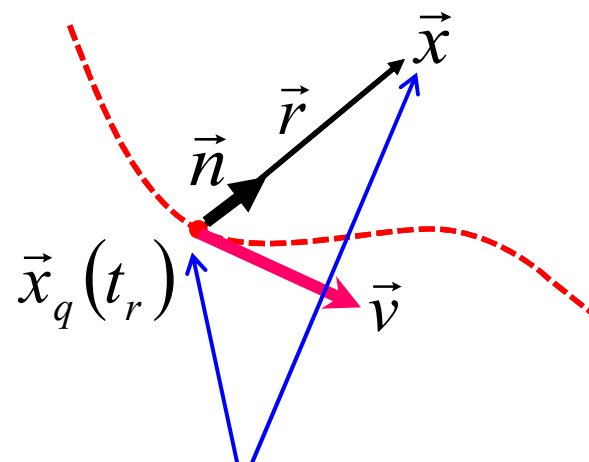
$$\left(1 - \frac{\vec{v} \cdot \vec{n}}{c}\right) \nabla t_r = -\frac{1}{c} \vec{n}$$

得到: 
$$\nabla t_r = -(c - \vec{v} \cdot \vec{n}) \vec{n}$$

$$\vec{r} = \vec{x} - \vec{x}_q(t_r)$$

$$t_r = t - \frac{r}{c}$$

$$\frac{\partial r}{\partial t_r} = -\vec{v} \cdot \vec{n}$$



$$t_r = t - \frac{r}{c}$$

$$\boxed{\nabla r} \quad \longrightarrow \quad \nabla r = -c \nabla t_r$$

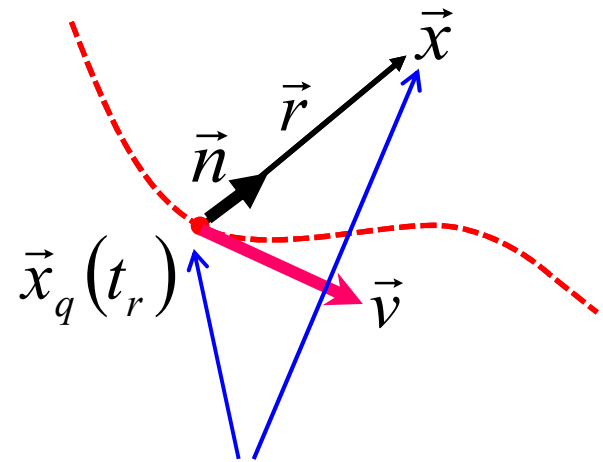
$$\nabla(\vec{r} \cdot \vec{v})$$

$$= (\vec{r} \cdot \nabla) \vec{v} + (\vec{v} \cdot \nabla) \vec{r} + \vec{r} \times (\nabla \times \vec{v}) + \vec{v} \times (\nabla \times \vec{r}) \quad (\text{教材附录 I. 23})$$

$$= \vec{v} + (\vec{r} \cdot \dot{\vec{v}} - v^2) \nabla t_r$$

(详细计算见课件的附录)

$$\text{其中: } \dot{\vec{v}} = \frac{d\vec{v}}{dt_r} \text{ (acceleration)}$$



$$\phi(\vec{x}, t) = \frac{1}{4\pi\epsilon_0} \cdot \frac{q}{r - \frac{1}{c} \vec{v} \cdot \vec{r}}$$

(1)  $\nabla\phi$  的计算

$$\phi(\vec{x}, t) = \frac{q}{4\pi\epsilon_0} s^{-1}, \quad \left( s \equiv r - \frac{\vec{r} \cdot \vec{v}}{c} \right)$$

$$\nabla\phi = \frac{q}{4\pi\epsilon_0} \nabla s^{-1}$$

$$t_r = t - \frac{r}{c}$$

$$\nabla r = -c \nabla t_r$$

$$\nabla \varphi = \frac{q}{4\pi\epsilon_0} \nabla s^{-1}$$

$$\nabla(\vec{r} \cdot \vec{v}) = \vec{v} + (\vec{r} \cdot \dot{\vec{v}} - v^2) \nabla t_r$$

$$\nabla s^{-1} = -s^{-2} \nabla \left( r - \frac{\vec{r} \cdot \vec{v}}{c} \right)$$

$$\left( s \equiv r - \frac{\vec{r} \cdot \vec{v}}{c} \right)$$

$$\nabla s^{-1} = -s^{-2} \left[ -c \nabla t_r - \frac{\vec{v} + (\vec{r} \cdot \dot{\vec{v}} - v^2) \nabla t_r}{c} \right]$$

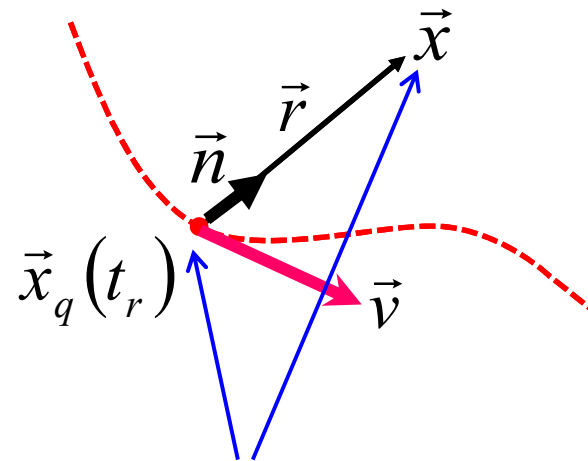
$$\nabla \varphi = -\frac{q}{4\pi\epsilon_0} s^{-2} \left[ -c \nabla t_r - \frac{\vec{v}}{c} - (\vec{r} \cdot \dot{\vec{v}} - v^2) \frac{\nabla t_r}{c} \right]$$

(2)  $\frac{\partial \vec{A}}{\partial t}$  的计算

$$\vec{A}(\vec{x}, t) = \frac{q}{4\pi\epsilon_0 c^2} \frac{\vec{v}}{s},$$

$$\left( s \equiv r - \frac{\vec{r} \cdot \vec{v}}{c} \right)$$

$$\frac{\partial(\vec{r} \cdot \vec{v})}{\partial t_r} = -\vec{v} \cdot \vec{v} + \vec{r} \cdot \dot{\vec{v}}$$





$$\vec{A}(\vec{x}, t) = \frac{q}{4\pi\epsilon_0 c^2} s^{-1} \vec{v}, \quad \frac{\partial(\vec{r} \cdot \vec{v})}{\partial t_r} = -\vec{v} \cdot \vec{v} + \vec{r} \cdot \dot{\vec{v}}$$

$$t_r = t - \frac{r}{c}$$

$$\frac{\partial \vec{A}}{\partial t} = \frac{\partial \vec{A}}{\partial t_r} \cdot \frac{\partial t_r}{\partial t}$$

$$\vec{r} = \vec{x} - \vec{x}_q(t_r)$$

$$\frac{\partial \vec{A}}{\partial t_r} = \frac{q}{4\pi\epsilon_0 c^2} \cdot \frac{\partial(s^{-1} \vec{v})}{\partial t_r} = \frac{q}{4\pi\epsilon_0 c^2} \left[ \frac{\partial s^{-1}}{\partial t_r} \vec{v} + s^{-1} \dot{\vec{v}} \right]$$

$$\left( s \equiv r - \frac{\vec{r} \cdot \vec{v}}{c} \right)$$

$$\frac{\partial r}{\partial t_r} = -\vec{v} \cdot \vec{n}$$

$$\begin{aligned} \frac{\partial s^{-1}}{\partial t_r} &= -s^{-2} \frac{\partial s}{\partial t_r} = -s^{-2} \left[ \frac{\partial r}{\partial t_r} - \frac{\partial(\vec{r} \cdot \vec{v})}{c \partial t_r} \right] \\ &= -s^{-2} \left( -\vec{v} \cdot \vec{n} + \frac{\vec{v} \cdot \vec{v} - \vec{r} \cdot \dot{\vec{v}}}{c} \right) \end{aligned}$$

$$\frac{\partial \vec{A}}{\partial t} = \frac{q}{4\pi\epsilon_0 c^2} \left[ -s^{-2} \vec{v} \left( -\vec{v} \cdot \vec{n} + \frac{\vec{v} \cdot \vec{v} - \vec{r} \cdot \dot{\vec{v}}}{c} \right) + s^{-1} \dot{\vec{v}} \right] \frac{\partial t_r}{\partial t}$$

(3)  $\nabla \times \vec{A}$  的计算

$$\vec{A} = \frac{q\vec{v}}{4\pi\epsilon_0 c^2} s^{-1}, \quad \left( s \equiv r - \frac{\vec{r} \cdot \vec{v}}{c} \right)$$

$$\nabla \times \vec{A} = \frac{q}{4\pi\epsilon_0 c^2} \nabla \times (s^{-1}\vec{v})$$

$$\nabla s^{-1} = -s^{-2} \left[ -c \nabla t_r - \frac{\vec{v} + (\vec{r} \cdot \dot{\vec{v}} - v^2) \nabla t_r}{c} \right]$$

$$\nabla \times \vec{A} = \frac{\mu_0 q}{4\pi} \nabla \times (s^{-1} \vec{v})$$

$$\rightarrow \nabla \times (s^{-1} \vec{v}) = (\nabla s^{-1}) \times \vec{v} + s^{-1} \nabla \times \vec{v}$$

$$\nabla \times \vec{v} = -\frac{d\vec{v}}{dt_r} \times \nabla t_r = -\dot{\vec{v}} \times \nabla t_r$$

$$\nabla \times \vec{A}$$

$$= \frac{q}{4\pi\epsilon_0 c^2} \left\{ -s^{-2} \left[ -c \nabla t_r - \frac{\vec{v} + (\vec{r} \cdot \dot{\vec{v}} - v^2) \nabla t_r}{c} \right] \times \vec{v} - s^{-1} \vec{v} \times \nabla t_r \right\}$$

$$\nabla \varphi = -\frac{q}{4\pi\epsilon_0} s^{-2} \left[ -c\nabla t_r - \frac{\vec{v}}{c} - (\vec{r} \cdot \dot{\vec{v}} - v^2) \frac{\nabla t_r}{c} \right]$$

$$\frac{\partial \vec{A}}{\partial t} = \frac{q}{4\pi\epsilon_0 c^2} \left[ -s^{-2} \vec{v} (-\vec{v} \cdot \vec{n} + \frac{\vec{v} \cdot \vec{v} - \vec{r} \cdot \dot{\vec{v}}}{c}) + s^{-1} \dot{\vec{v}} \right] \frac{\partial t}{\partial t_r}$$

$$\nabla \times \vec{A} = \frac{q}{4\pi\epsilon_0 c^2} \left\{ -s^{-2} \left[ -c\nabla t_r - \frac{\vec{v}}{c} - (\vec{r} \cdot \dot{\vec{v}} - v^2) \frac{\nabla t_r}{c} \right] \times \vec{v} - s^{-1} (\dot{\vec{v}} \times \nabla t_r) \right\}$$

# 一) 讨论当粒子速度 $v \ll c$ 时所激发的电磁场

$$\nabla t_r = -\left(c - \vec{v} \cdot \vec{n}\right)^{-1} \vec{n}$$

$$\nabla t_r \approx -\frac{\vec{n}}{c}$$

$$\frac{\partial t_r}{\partial t} = \left(1 - \frac{\vec{v} \cdot \vec{n}}{c}\right)^{-1}$$

$$\frac{\partial t_r}{\partial t} \approx 1$$

$$\left(s \equiv r - \frac{\vec{r} \cdot \vec{v}}{c}\right)$$

$$s \equiv r - \frac{\vec{r} \cdot \vec{v}}{c} \approx r$$

$$s \approx r$$

$$\nabla t_r \approx -\frac{\vec{n}}{c}$$

$$\frac{\partial t_r}{\partial t} \approx 1$$

$$\nabla \varphi = -\frac{q}{4\pi\epsilon_0} s^{-2} \left[ -c\nabla t_r - \frac{\vec{v}}{c} - (\vec{r} \cdot \dot{\vec{v}} - v^2) \frac{\nabla t_r}{c} \right]$$

$$\approx -\frac{q}{4\pi\epsilon_0} r^{-2} \left[ \vec{n} - \cancel{\frac{\vec{v}}{c}} + (\vec{r} \cdot \dot{\vec{v}} - \cancel{v^2}) \frac{\vec{n}}{c^2} \right]$$

$$\nabla \varphi \approx -\frac{q}{4\pi\epsilon_0} \frac{1}{r^2} \vec{n} - \frac{q}{4\pi\epsilon_0} \frac{\vec{r} \cdot \dot{\vec{v}}}{r^2 c^2} \vec{n}$$

$$\nabla t_r \approx -\frac{\vec{n}}{c}$$

$$\frac{\partial t_r}{\partial t} \approx 1$$

$$s \approx r$$

$$\frac{\partial \vec{A}}{\partial t} = \frac{q}{4\pi\epsilon_0 c^2} \left[ -s^{-2} \left( -\vec{v} \cdot \vec{n} + \frac{\vec{v} \cdot \vec{v} - \vec{r} \cdot \dot{\vec{v}}}{c} \right) \vec{v} + s^{-1} \dot{\vec{v}} \right] \frac{\partial t}{\partial t_r}$$

$$\approx \frac{q}{4\pi\epsilon_0} \left[ -\frac{1}{r^2} \left( -\vec{v} \cdot \vec{n} + \frac{\vec{v} \cdot \vec{v} - \vec{r} \cdot \dot{\vec{v}}}{c} \right) \vec{v} + \frac{1}{r} \dot{\vec{v}} \right]$$

$$= \frac{q}{4\pi\epsilon_0} \left[ -\frac{1}{r^2} \left( -\vec{v} \cdot \vec{n} + \frac{\vec{v} \cdot \vec{v} - \vec{r} \cdot \dot{\vec{v}}}{c} \right) \frac{\vec{v}}{c^2} + \frac{1}{r} \frac{\dot{\vec{v}}}{c^2} \right]$$

$$\frac{\partial \vec{A}}{\partial t} \approx \frac{q}{4\pi\epsilon_0} \frac{\dot{\vec{v}}}{rc^2}$$

$$\nabla\varphi \approx -\frac{q}{4\pi\epsilon_0} \frac{1}{r^2} \vec{n} - \frac{q}{4\pi\epsilon_0} \frac{\vec{n}}{r^2 c^2} \vec{r} \cdot \dot{\vec{v}}$$

$$\vec{E} = -\nabla\varphi - \frac{\partial \vec{A}}{\partial t}$$

$$\frac{\partial \vec{A}}{\partial t} \approx \frac{q}{4\pi\epsilon_0} \frac{\dot{\vec{v}}}{rc^2}$$

$$\approx \frac{q}{4\pi\epsilon_0} \frac{1}{r^2} \vec{n} + \frac{q}{4\pi\epsilon_0} \frac{\vec{n}}{r^2 c^2} \vec{r} \cdot \dot{\vec{v}} - \frac{q}{4\pi\epsilon_0} \frac{\dot{\vec{v}}}{rc^2}$$

$$= \frac{q}{4\pi\epsilon_0} \frac{1}{r^2} \vec{n} + \frac{q}{4\pi\epsilon_0 c^2} \left( \frac{\vec{n}}{r^2} \vec{r} \cdot \dot{\vec{v}} - \frac{\dot{\vec{v}}}{r} \right)$$

$$= \frac{q}{4\pi\epsilon_0} \frac{1}{r^2} \vec{n} + \frac{q}{4\pi\epsilon_0 c^2} \frac{1}{r^3} \left[ \vec{r} (\vec{r} \cdot \dot{\vec{v}}) - \dot{\vec{v}} (\vec{r} \cdot \vec{r}) \right]$$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1}{r^2} \vec{n} + \frac{q}{4\pi\epsilon_0 c^2} \frac{1}{r^3} \vec{r} \times (\vec{r} \times \dot{\vec{v}})$$



$$\vec{B} = ?$$

$$\nabla t_r \approx -\frac{\vec{n}}{c}$$

$$\frac{\partial t_r}{\partial t} \approx 1$$

$$s \approx r$$

$$\nabla \times \vec{A} = \frac{q}{4\pi\epsilon_0 c^2} \left\{ -s^{-2} \left[ -c\nabla t_r - \frac{\vec{v}}{c} - (\vec{r} \cdot \dot{\vec{v}} - v^2) \frac{\nabla t_r}{c} \right] \times \vec{v} - s^{-1} (\dot{\vec{v}} \times \nabla t_r) \right\}$$

$$\approx \frac{q}{4\pi\epsilon_0 c^2} \left\{ \frac{-1}{r^2} \left[ \vec{n} - \frac{\vec{v}}{c} + (\vec{r} \cdot \dot{\vec{v}} - v^2) \frac{\vec{n}}{c^2} \right] \times \vec{v} + \frac{1}{r} \dot{\vec{v}} \times \frac{\vec{n}}{c} \right\}$$

$$\approx \frac{q}{4\pi\epsilon_0 c^2} \left( \frac{-1}{r^2} \vec{n} \times \vec{v} + \frac{1}{r} \dot{\vec{v}} \times \frac{\vec{n}}{c} \right)$$

$$\vec{B} = \frac{1}{4\pi\epsilon_0 c^2} \frac{q\vec{v} \times \vec{r}}{r^3} + \frac{q}{4\pi\epsilon_0 c^3} \frac{\dot{\vec{v}} \times \vec{r}}{r^2}$$

在  $v \ll c$  情况下:

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1}{r^2} \vec{n} + \frac{q}{4\pi\epsilon_0 c^2} \frac{1}{r^3} \vec{r} \times (\vec{r} \times \dot{\vec{v}})$$

$$\vec{B} = \frac{1}{4\pi\epsilon_0 c^2} \frac{q\vec{v} \times \vec{r}}{r^3} + \frac{q}{4\pi\epsilon_0 c^3} \frac{\dot{\vec{v}} \times \vec{r}}{r^2}$$

**结论：** 在  $v \ll c$  情况下：

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\vec{r}}{r^3} + \frac{q}{4\pi\epsilon_0 c^2} \frac{1}{r^3} \vec{r} \times (\vec{r} \times \dot{\vec{v}})$$
$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q\vec{v} \times \vec{r}}{r^3} + \frac{q}{4\pi\epsilon_0 c^3} \frac{\dot{\vec{v}} \times \vec{r}}{r^2}$$

静场项

Static term

动力学项

Dynamic term

在  $v \ll c$  情况下:

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\vec{r}}{r^3} + \frac{q}{4\pi\epsilon_0 c^2} \frac{1}{r^3} \vec{r} \times (\vec{r} \times \dot{\vec{v}})$$
$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q\vec{v} \times \vec{r}}{r^3} + \frac{q}{4\pi\epsilon_0 c^3} \frac{\dot{\vec{v}} \times \vec{r}}{r^2}$$

静场项  $\propto r^{-2}$

➤ 对于匀速运动 ➔ 非辐射场

在  $v \ll c$  情况下:

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\vec{r}}{r^3} + \frac{q}{4\pi\epsilon_0 c^2} \frac{1}{r^3} \vec{r} \times (\vec{r} \times \dot{\vec{v}})$$

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q\vec{v} \times \vec{r}}{r^3} + \frac{q}{4\pi\epsilon_0 c^3} \frac{\dot{\vec{v}} \times \vec{r}}{r^2}$$

辐射场  $\propto r^{-1}$

➤ 加速运动 → 辐射场

附录： $\nabla(\vec{r} \cdot \vec{v})$  的详细计算推导

$$\nabla(\vec{r} \cdot \vec{v}) = \underline{(\vec{r} \cdot \nabla)\vec{v}} + \underline{(\vec{v} \cdot \nabla)\vec{r}} + \underline{\vec{r} \times (\nabla \times \vec{v})} + \underline{\vec{v} \times (\nabla \times \vec{r})} \quad (1.23)$$

第一项：

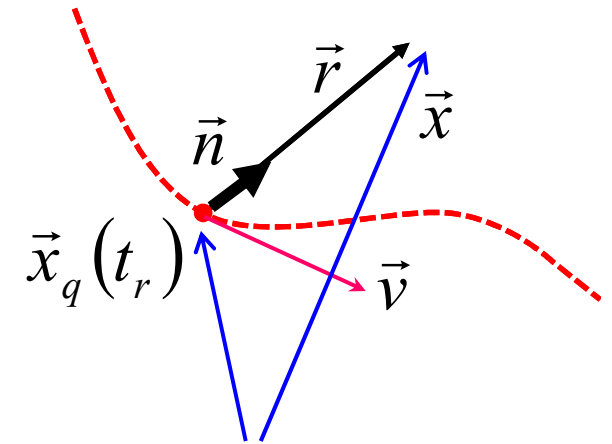
$$\begin{aligned} (\vec{r} \cdot \nabla)\vec{v} &= \left( r_x \frac{\partial}{\partial x} + r_y \frac{\partial}{\partial y} + r_z \frac{\partial}{\partial z} \right) \vec{v}(t_r) \\ &= r_x \frac{d\vec{v}}{dt_r} \frac{\partial t_r}{\partial x} + r_y \frac{d\vec{v}}{dt_r} \frac{\partial t_r}{\partial y} + r_z \frac{d\vec{v}}{dt_r} \frac{\partial t_r}{\partial z} \\ &= \dot{\vec{v}}(\vec{r} \cdot \nabla t_r) \end{aligned}$$

$$\nabla(\vec{r} \cdot \vec{v}) = (\vec{r} \cdot \nabla)\vec{v} + (\vec{v} \cdot \nabla)\vec{r} + \vec{r} \times (\nabla \times \vec{v}) + \vec{v} \times (\nabla \times \vec{r})$$

第二项:  $(\vec{v} \cdot \nabla)\vec{r} = (\vec{v} \cdot \nabla)\vec{x} - (\vec{v} \cdot \nabla)\vec{x}_q(t_r)$

$$\begin{aligned} (\vec{v} \cdot \nabla)\vec{x} &= \left( v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z} \right) (x, y, z) \\ &= v_x \frac{\partial(x, y, z)}{\partial x} + v_y \frac{\partial(x, y, z)}{\partial y} + v_z \frac{\partial(x, y, z)}{\partial z} \\ &= v_x (1, 0, 0) + v_y (0, 1, 0) + v_z (0, 0, 1) = (v_x, v_y, v_z) = \vec{v} \end{aligned}$$

$$\begin{aligned} (\vec{v} \cdot \nabla)\vec{x}_q &= \left( v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z} \right) \vec{x}_q \\ &= v_x \frac{d\vec{x}_q}{dt_r} \frac{\partial t_r}{\partial x} + v_y \frac{d\vec{x}_q}{dt_r} \frac{\partial t_r}{\partial y} + v_z \frac{d\vec{x}_q}{dt_r} \frac{\partial t_r}{\partial z} = \vec{v} (\vec{v} \cdot \nabla t_r) \end{aligned}$$



$$\vec{r} = \vec{x} - \vec{x}_q(t_r)$$

$$\frac{d\vec{x}_q}{dt_r} = \vec{v}$$

$$(\vec{v} \cdot \nabla)\vec{r} = \vec{v} - \vec{v}(\vec{v} \cdot \nabla t_r)$$

$$\nabla(\vec{r} \cdot \vec{v}) = \underline{(\vec{r} \cdot \nabla)\vec{v}} + \underline{(\vec{v} \cdot \nabla)\vec{r}} + \underline{\vec{r} \times (\nabla \times \vec{v})} + \underline{\vec{v} \times (\nabla \times \vec{r})}$$

第三项中：

$$\nabla \times \vec{v} = \nabla \times \vec{v}(t_r) = -\frac{d\vec{v}}{dt_r} \times \nabla t_r = -\dot{\vec{v}} \times \nabla t_r$$

第四项中：

$$\begin{aligned}\nabla \times \vec{r} &= \nabla \times \vec{x} - \nabla \times \vec{x}_q = 0 - \nabla \times \vec{x}_q \\ &= \frac{d\vec{x}_q}{dt_r} \times \nabla t_r = \vec{v} \times \nabla t_r\end{aligned}$$



把上面的结果带入：

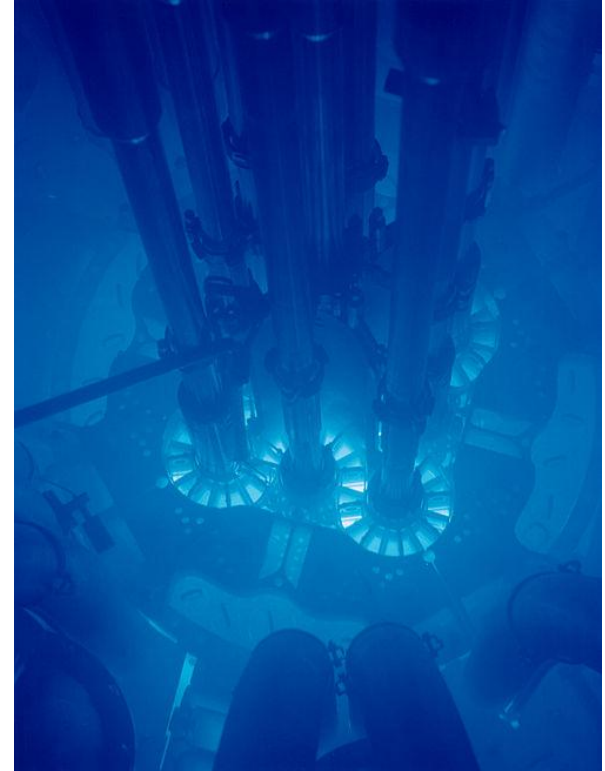
$$\begin{aligned} & \nabla(\vec{r} \cdot \vec{v}) \\ &= (\vec{r} \cdot \nabla)\vec{v} + (\vec{v} \cdot \nabla)\vec{r} + \vec{r} \times (\nabla \times \vec{v}) + \vec{v} \times (\nabla \times \vec{r}) \\ &= \dot{\vec{v}}(\vec{r} \cdot \nabla t_r) + \vec{v} - \vec{v}(\vec{v} \cdot \nabla t_r) - \vec{r} \times (\dot{\vec{v}} \times \nabla t_r) + \vec{v} \times (\vec{v} \times \nabla t_r) \\ &= \dot{\vec{v}}(\vec{r} \cdot \nabla t_r) + \vec{v} - \vec{v}(\vec{v} \cdot \nabla t_r) - (\vec{r} \cdot \nabla t_r)\dot{\vec{v}} + (\vec{r} \cdot \dot{\vec{v}})\nabla t_r \\ & \quad + (\vec{v} \cdot \nabla t_r)\vec{v} - (\vec{v} \cdot \vec{v})\nabla t_r \end{aligned}$$

约去相消项得：

$$\nabla(\vec{r} \cdot \vec{v}) = \vec{v} + (\vec{r} \cdot \dot{\vec{v}})\nabla t_r - (\vec{v} \cdot \vec{v})\nabla t_r$$

所以：

$$\nabla(\vec{r} \cdot \vec{v}) = \vec{v} + (\vec{r} \cdot \dot{\vec{v}} - v^2)\nabla t_r$$



Cherenkov radiation glowing in the core of the Advanced Test Reactor